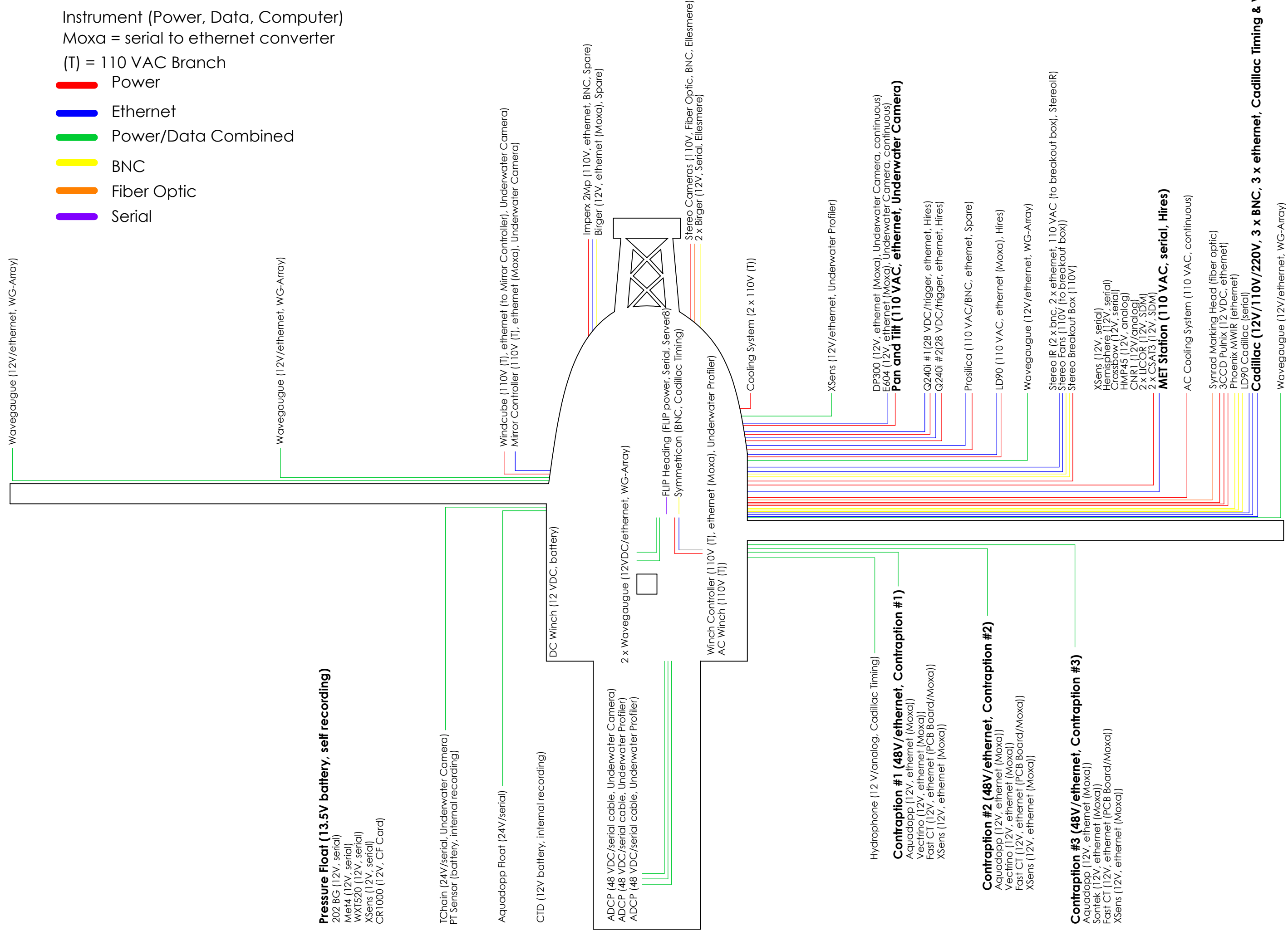


- Instrument (Power, Data, Computer)  
Moxa = serial to ethernet converter  
(T) = 110 VAC Branch
- █ Power
  - █ Ethernet
  - █ Power/Data Combined
  - █ BNC
  - █ Fiber Optic
  - █ Serial



**Pressure Float (13.5V battery, self recording)**

- 202.BG (12V, serial)
- Mei4 (12V, serial)
- WXT520 (12V, serial)
- XSens (12V, serial)
- CR1000 (12V, CF Card)

TChain (24V/serial, Underwater Camera)  
PT Sensor (battery, internal recording)

Aquadopp Float (24V/serial)

CTD (12V battery, internal recording)

DC Winch (12 VDC, battery)

ADCP (48 VDC/serial cable, Underwater Camera)  
ADCP (48 VDC/serial cable, Underwater Profiler)  
ADCP (48 VDC/serial cable, Underwater Profiler)

2 x Wavegaugue (12VDC/ethernet, WG-Array)

Winch Controller (110V (T), ethernet (Moxa), Underwater Profiler)  
AC Winch (110V (T))

Hydrophone (12 V/analog, Cadillac Timing)

**Contraption #1 (48V/ethernet, Contraption #1)**

- Aquadopp (12V, ethernet (Moxa))
- Vecfino (12V, ethernet (Moxa))
- Fast CT (12V, ethernet (PCB Board/Moxa))
- XSens (12V, ethernet (Moxa))

**Contraption #2 (48V/ethernet, Contraption #2)**

- Aquadopp (12V, ethernet (Moxa))
- Vecfino (12V, ethernet (Moxa))
- Fast CT (12V, ethernet (PCB Board/Moxa))
- XSens (12V, ethernet (Moxa))

**Contraption #3 (48V/ethernet, Contraption #3)**

- Aquadopp (12V, ethernet (Moxa))
- Sonitek (12V, ethernet (Moxa))
- Fast CT (12V, ethernet (PCB Board/Moxa))
- XSens (12V, ethernet (Moxa))

**MET Station (110 VAC, serial, Hires)**

AC Cooling System (110 VAC, continuous)

- Synrad Marking Head (fiber optic)
- 3CCD Pulnix (12 VDC, ethernet)
- Phoenix MWIR (ethernet)
- LD90 Cadillac (serial)

**Cadillac (12V/110V/220V, 3 x BNC, 3 x ethernet, Cadillac Timing & Video)**

Wavegaugue (12V/ethernet, WG-Array)